

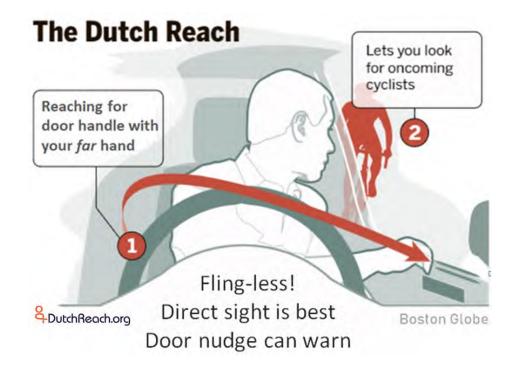
An Introduction to LinSig

Roger Dickinson Jacob Hughes



Safety Moment

- Raise your hand if you check your blind spot when exiting the car.
- Raise your hand if you ride a bike and have had a car door open on you.
- In the UK between 2004 and 2020, serious injuries (adjusted) rose by 26% whilst pedal cycle traffic grew by 96% in this same period.
- The 3 most common contributory factor assigned to both pedal cyclists and other vehicle types was 'failed to look properly' followed by a failure 'to judge other person's path or speed' and 'Driver or rider careless, reckless or in a hurry'.
- A method known as the "Dutch reach" has been introduced to the Highway Code in the UK; The practice is used widely across Europe and encourages people to open vehicle doors with their opposite hand to avoid injuries to passing cyclists.



- My name is Jacob Hughes and I have been using LinSig for 7 years, working for AECOM throughout that time.
- Based in the Manchester office, though been part of Bristol and Exeter Streets teams too.
- Modelled many complex signalised junctions and networks across the UK and Ireland.
- Provides checking/verification of internal modelling deliverables and thorough audit checks of external models.
- Have run the AECOM LinSig training courses alongside Roger since 2018.
- Please place any questions you have in the chat.





Who am I?

- My name is Roger Dickinson and I have been using LinSig for 25 years.
- Worked for AECOM for over 22 years. Based in the Exeter office
- Seconded to Transport for London for 3 years
- Modelled many complex signalised junctions and networks across the UK and Ireland.
- Have run the AECOM LinSig training courses since 2012.
- Please place any questions you have in the chat.





What will this LinSig Presentation will cover

It will introduce the LinSig modelling software programme and cover:

- Basic Modelling Theory
- Data Input
- Model Validation
- Model Results
- Other features

Due to time limitations, we will not cover the process of building a LinSig model in detail.





What is LinSig and how it works



What is LinSig?

LinSig is a traffic modelling software tool used to assess the capacity of signalised junctions and small / medium sized networks, including roundabouts. It can also model priority-controlled junctions and roundabouts.

It has been developed by JCT Consultancy, who are based in Lincoln.

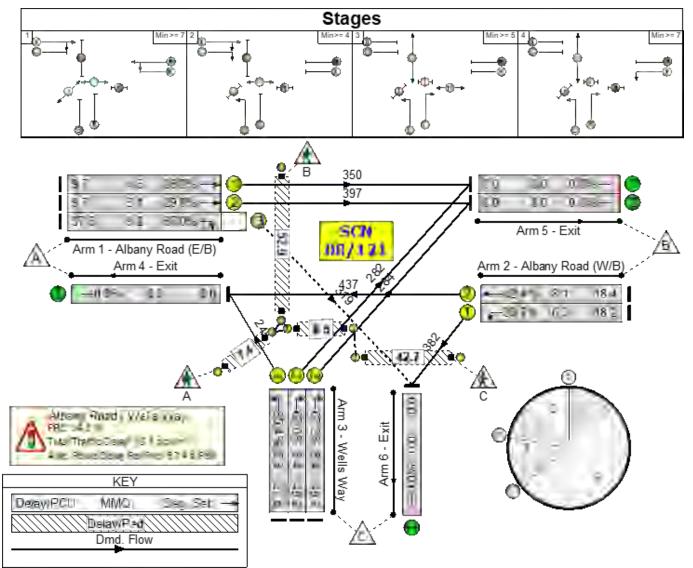
It allows the user to assess potential changes to the junctions relatively easily and has the ability to quickly eliminate unfeasible options before design work is undertaken.

It is compatible with how Signal Controllers work

Also has a SCATS-based controller model and is widely used in Australia and New Zealand.

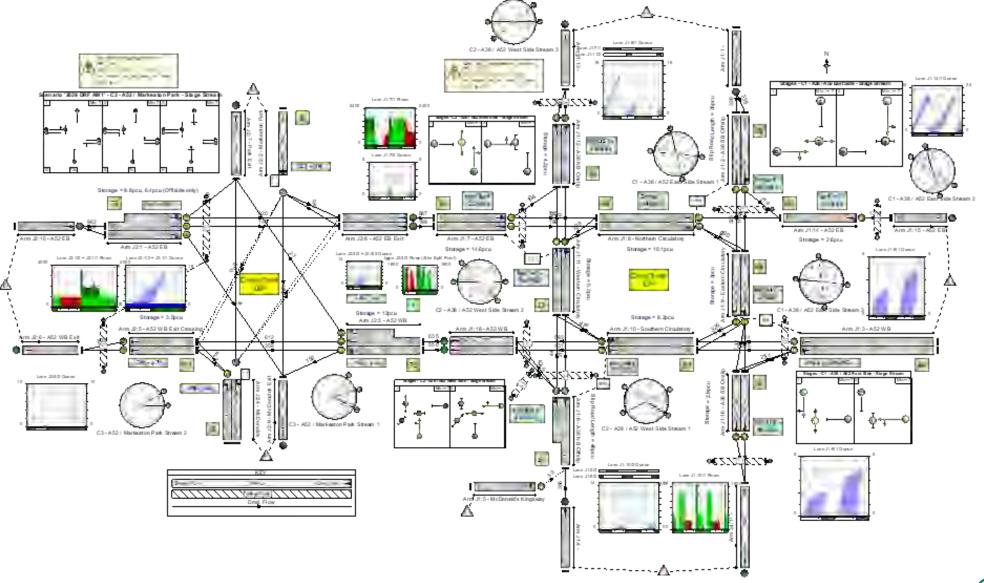


What is the scope of a LinSig model?

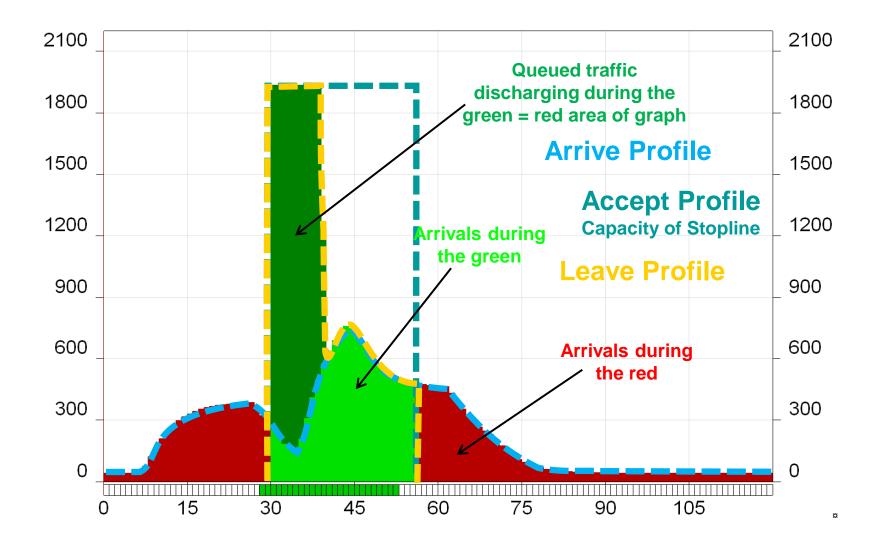




What is the scope of a LinSig model?

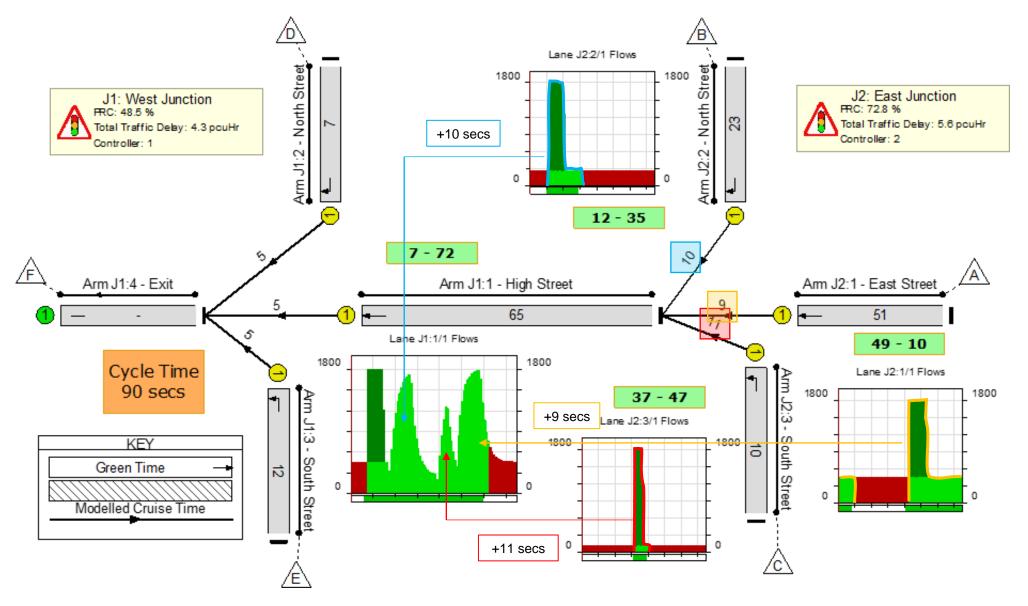


LinSig Theory – Flow Profile Graph





Leave (flow) profiles moving through the network





LinSig Degree of Saturation & Practical Reserve Capacity

Degree of Saturation (DoS, %) is the proportion of how saturated a lane is compared to its capacity.

LinSig considers any lane over 90% DoS to be oversaturated (highlighting it in red) and provides a negative Practical Reserve Capacity (PRC, %) for the junction. PRC results per junction are based on the lane with the worst DoS.



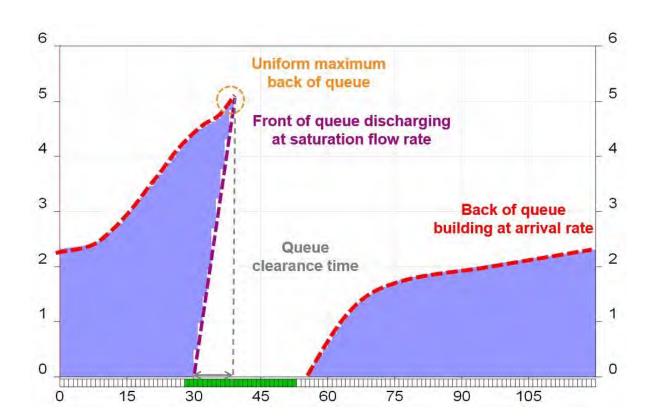
LinSig Queuing Graph

Uniform Queuing (DoS < 80%)

- Queue grows and clears every cycle
- Oversaturated Queuing (DoS > 110%)
- A residual queue remains at the end of the cycle and is carried over to the next cycle

Random Queuing (DoS between 80% & 110%)

 Random variations from cycle to cycle whereby a different number of vehicles get through the stopline





LinSig Queuing

Mean Max Queue (MMQ)

- Maximum Back of Queue + Oversaturated & Random Queue
- The average value, over the peak hour, of the maximum queues occurring each cycle
- It is therefore difficult to validate the queue values against observations
- Queues less than ³/₄ of the available storage area are considered to contain the queue every cycle.
- Any MMQ exceeding the lane length will be highlighted red by LinSig.



Limitations of LinSig

- LinSig models an average cycle during the modelled hour, so it doesn't replicate variations to traffic during the peak hour.
- Traffic entering the network is assumed to arrive with a flat profile across the cycle / peak hour.
- Queues in the LinSig model are assumed to stack "vertically", so if a downstream link is full, the model will still send traffic through. It is not a microsimulation model. However, the use of Bonus Greens could be used to replicate how much effective green is available to replicate the downstream blockage.

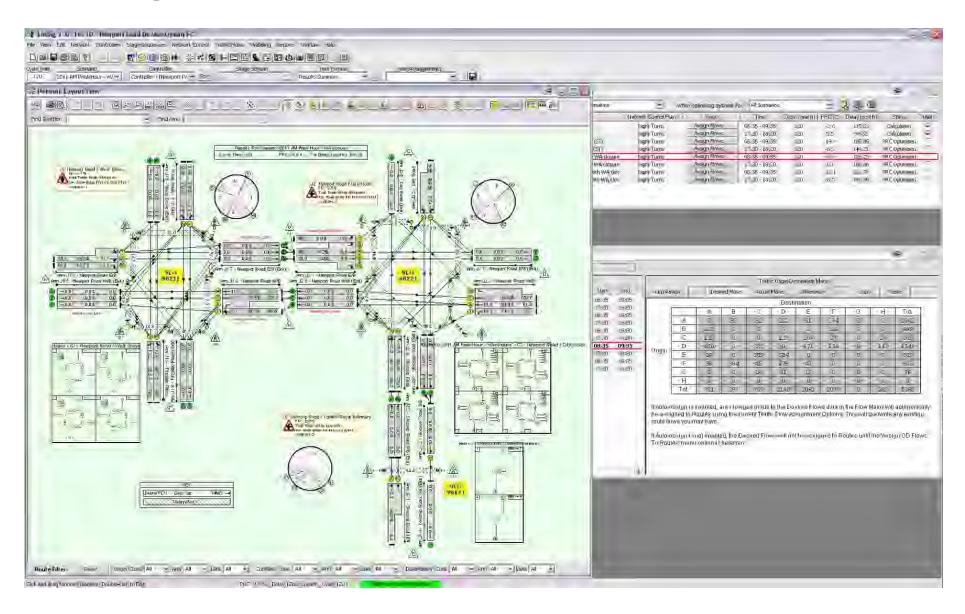




What data is required for a LinSig model



What does LinSig look like?





Data Input – Information Needed

Network Information

- Signal Layout Drawing (lane widths, lane lengths, turning radii)
- Saturation Flows (lane capacities)
- Signal Information
- For an existing Junction:
 - Controller Specification Document (phases, stages, intergreens, phase delays & prohibited stage movements)
 - Signal Output Data (observed stage lengths, offsets, variable on-site intergreen times and demand dependency)
- For new junctions, these will need to be determined / calculated



Data Input – Information Needed

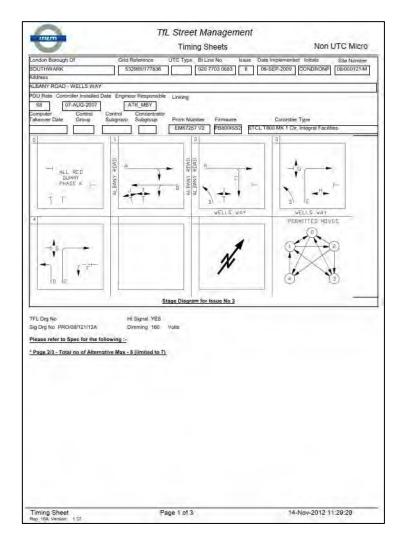
Site Visit

- Determine lane usage or flare (short lane) usage
- Vehicle behaviors (using the lanes they should)
- Saturation flows surveys (lane capacities)
- Under-utilised green time (exit blocking)
- Confirm or collect signal timings
- Cruise times (uncongested time between stoplines)



Examples of Controller Specification Documents

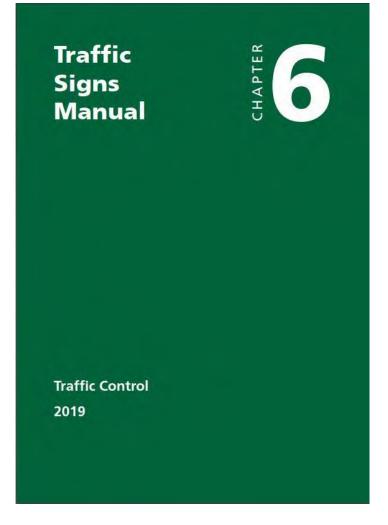
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Calculation of Signal Information

- Chapter 6 of the Traffic Signs Manual (Traffic Control) 2019 is the guide to the modelling of signalised junctions in the UK.
- Transport for London also has some of it's own guidance
- It has a lot of information, including the calculation of intergreen times for vehicle, cycle and pedestrian phases (the safe time gap for one phase to stop and the next to start)



Data Input – Traffic Flows

- There are two methods Matrix Based or Lane Based flows
- Zones need to be created for each entry / exit point
- A powerful matrix estimation tool can be used to create flow matrix from individual junction turning counts
- The flows between junctions need to be fairly consistent to give an accurate matrix
- Flows are then assigned to available routes by a delay-based assignment
- Flows on routes can be fixed (i.e. bus lanes or observed unequal lane usage)



Data Input – Traffic Flows

LinSig has a **formula flow function** that allows flow matrices to be factored up and matrices added to other matrices (i.e. base + development traffic)

Base traffic flows

- From observed traffic surveys, so DoS values should be <100%
- If junction is operating over capacity, you can add queuing traffic back into the model. Future year traffic flows
- These could be from a strategic highway model
- So you need to be consistent junction capacities between the two models
- Some iterations between the two may be needed



Data Input – Other mode flows

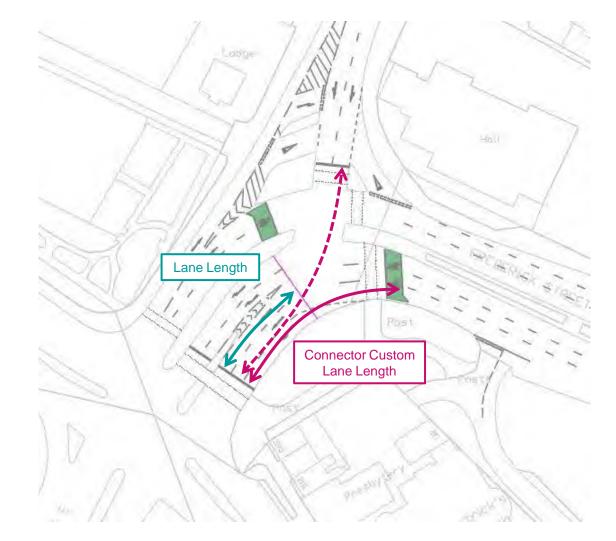
- Buses can be input separately (with their own zones, bus speeds and time at bus stops)
- Cycle lane flows can be input with the traffic or with their own zones, but it is not possible to have separate cycle cruise speeds if they are mixed with traffic
- Pedestrian flows across junctions can be modelled. If not known, default values (i.e. 10 pedestrians per route) can be used to determine average delay per pedestrian



Data Input – Cruise Times

A key part of the model is how long it takes vehicles to get from one stopline to the next

- Measured from site observations (average of 10 readings, but vehicles must not be delayed)
- Calculated from average cruise speeds and travel distances (stopline to stopline distance and average speed for the movement)





LinSig Input

The majority of lane information is input in the Edit Lane box on the Network Layout View screen

General ane Details Sat. flow data	Geometric Calculated Lane Saturation Flow (Arm Lane 2) Lane Width (m) 3.00 Gradient 0.00	C Directly Entered Lane Saturation Flow (Arm Lane 2) Default Saturation Flow (PCU/Hr) 1800		
Multi-Lane Advanced Flows: General Traffic Movmt to 31:9/2 (Ahead) Movmt to 31:10/1 (Right)	Treat as Nearside Lane 🔽 Click to specify Turning Radius for each movement on this lane	Flow Group PM Peak	Sat Flow Default	
	To Calculated Turn Prop. Radius (m) Arm J1:9 (Ah 62.2 % Inf Arm J1:10 (Ri 37.8 % 8.27			
	Calculated Turning Proportions are for Current Flow Group Geometric Calculated Lane Saturation Flow For Current Flow Group (PCU/Hr)	C Unconstrained (Infinite Saturation Flow) Selecting this format bottlenack- and lanes extend themetwat- will ensure no delay is incurred on them.		

Connectors are where the stopline to stopline journey times are calculated

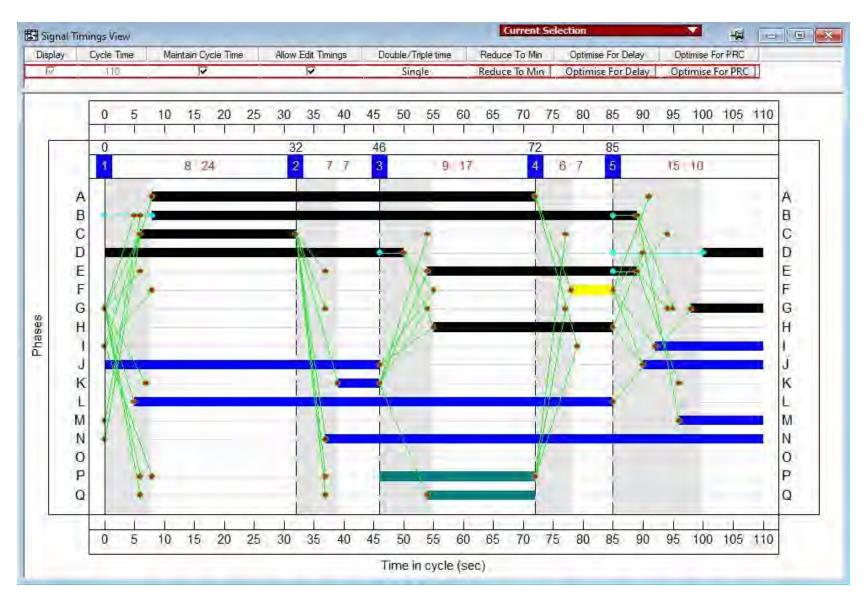
dit Lane Connector		×
General Row Detail Overrides		
From Lane 11.5/1 +		
Ta J1:3/1 +	Allow Routes to use this Connector	
Default cruise time through this Lane I These defaults will be used for all Row this Lane Connector unless otherwise	Groups and all Routes and Layers through	
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Custom Lane Length(m).	Use custom lane length för cruise time/speed calculations on this Connector	l
When modelling buses		L
Mean Bus Stopped Time (s) 15	Bus Speed (km/hr) 39	
Platoon Dispersion		
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Platoon Dispersion Coefficient 3	5.	
	OK Cancel	1



Signal Timings



Signal Timings





Modelling the Effective Green

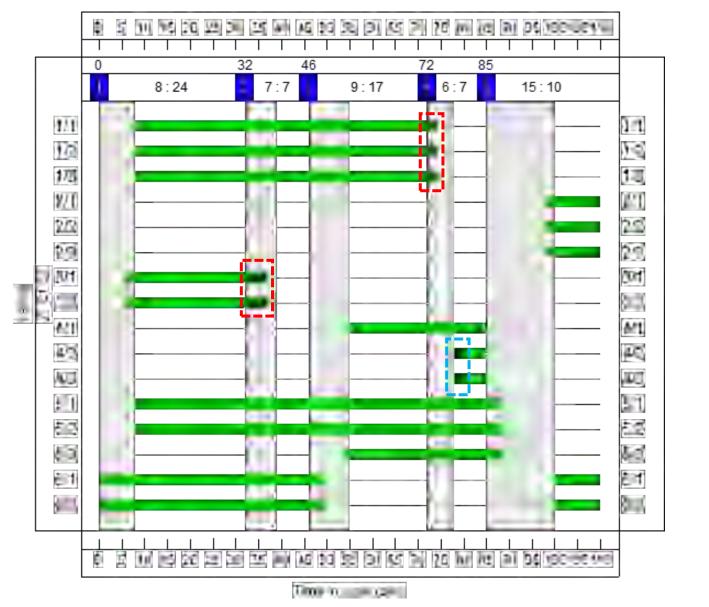
The use of Bonus Greens can allow the effective green (the amount of green time observed over the modelled hour) to be replicated. It is used in the following scenarios:

- Demand Dependent Stages that don't get called every cycle (reallocating green time)
- Under-utilised Green Time (exit blocking leads to traffic being unable to move through the stopline)
- A cycle advanced stop line delaying when the vehicles behind can start

The values are only applied to traffic lanes.



Modelling the Effective Green









Model Validation

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Base Model Validation

- Ensure models have the right capacity (saturation flow surveys if possible)
- Signal timings should be collected at the same time as the traffic surveys
- Junctions which operate under MOVA or VA control can be difficult to model as the green times and cycle time can vary throughout the modelled hour



Base Model Validation

Degree of Saturation

• Modelled values can be compared against observations for each stopline

Queue Length

- Observations can be compared, but you need to make sure they have been collected correctly
- The Mean-Max Queue is the average of all the maximum queues across the peak hour
- Comparing observed queues to queue graphs per lane
 Journey times
- Can be done from zone to zone
- They can also be determined from stopline to stopline
- Can include buses and cycles (if modelled separately)





Signal Optimisation



Signal Timing Optimisation

- Optimise signal timings for both Delay and PRC (Practical Reserve Capacity). PRC is linked to the DoS values.
- Optimise for Green Splits and Offsets (all timings) or just offsets (keeps the stage lengths the same) for networks
- You can fix specific stage lengths before optimising. You can also lock the offset of when Stage 1 starts
- Optimiser weightings can ensure key movements are prioritised when the signals are optimised.
- There is a Cycletime Optimisation View that runs the models with a variety of cycle times.





Understanding LinSig Results



LinSig Results

Network (or individual junction) Parameters

- Practical Reserve Capacity (positive value means all DoS values are under 90%)
- Total Delay

Lane Parameters

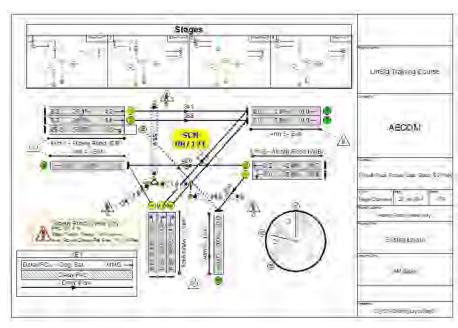
- Degree of Saturation (aim to get under 90%)
- Mean Max Queue (aim to get them under 75% of the available storage area)
- Delays

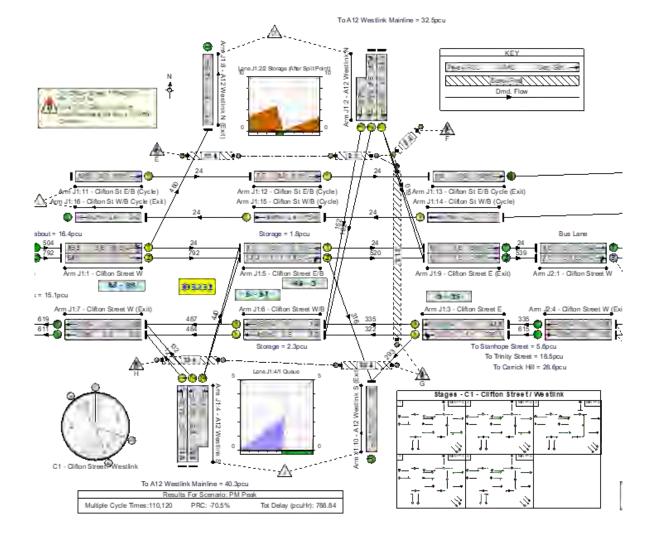
DoS values may be under 90%, but the queues can be more than the storage!



LinSig Results

- Report Generator
- Network Layout View. Create your own text formats. Red Text (over capacity)
- Print Layout Mode





LinSig Traffic Results – Example Table

Ref	Lane	Flow (pcu)	Degree of Saturation	Delay (s/pcu)	Mean Max Queue (pcu)		
1/1	Albany Road (E/B) Ahead	338	24.4%	6.3	3.4		
1/2	Albany Road (E/B) Ahead	391	26.3%	6.3	3.9		
1/3	Albany Road (E/B) Right	289	51.2%	21.0	5.1		
2/1	Albany Road (W/B) Left	329	22.0%	3.9	2.3		
2/2	Albany Road (W/B) Ahead	426	36.0%	13.2	6.6		
3/1	Wells Way Left	176	32.0%	33.1	4.1		
3/2	Wells Way Right	217	72.8%	62.8	7.2		
3/3	Wells Way Right	218	72.8%	62.7	7.2		
	Cycl	e Time		104 secs			
	Practical Res	serve Capacity	+23.6%				
	Tota	l Delay		14.08 pcuHr			



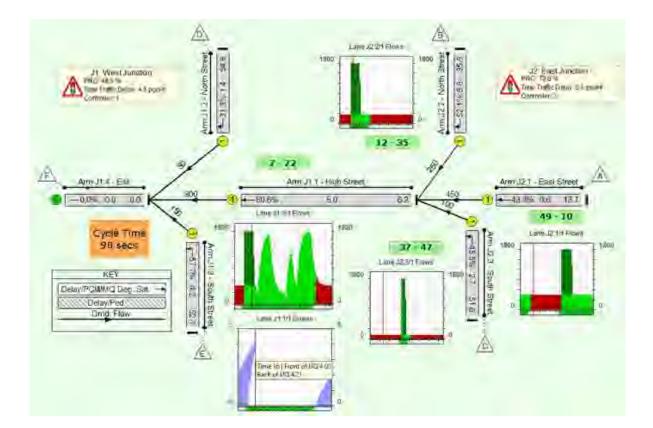
LinSig Results

Flow Graphs

 Used to see when different platoons of vehicles arrive at downstream stoplines

Queue Graphs

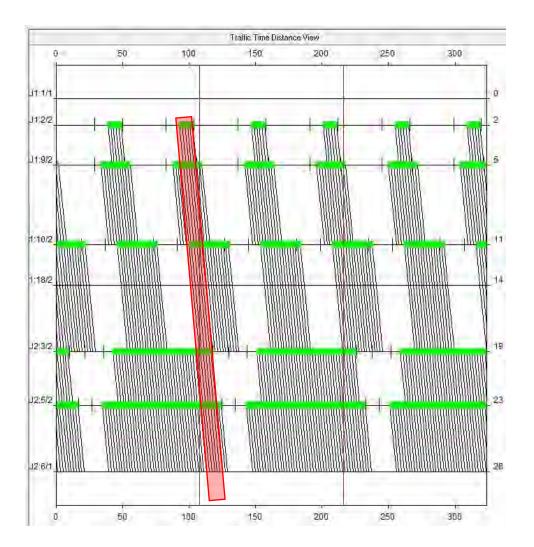
- Used to see when during the cycle the maximum queue length is likely to occur
- If queues reach an upstream junction the graph will indicate when in the cycle it occurs





LinSig Results – Delays and Journey Times

- Zone to Zone Route Delays and Journey times (total and average per pcu)
- Journey times for discrete sections of a wider route can be determined manually by adding stopline delays to the cruise times for the section in question.
- Time Distance Diagrams to see how well the vehicle movements co-ordinate through the network



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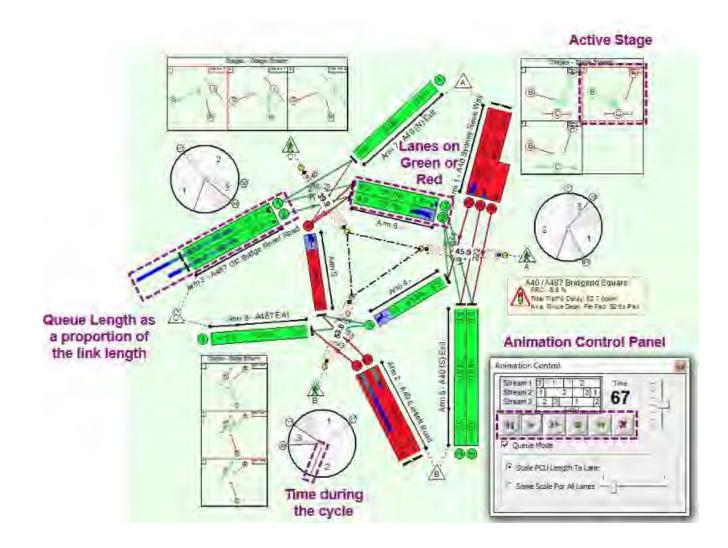
LinSig Results – Pedestrian Journey Times

Movement		Base (sec)	Proposed (sec)	Difference (sec)
A to B	SW to N	84.12	84.91	+0.79
A to C	SW to SE	81.78	82.13	+0.35
B to A	N to SW	72.11	71.91	-0.20
B to C	N to SE	157.23	149.34	-7.89
C to A	SE to SW	81.85	81.14	-0.71
C to B	SE to N	160.30	152.35	-7.95
Average		106.23	103.63	-2.60

Pedestrian journey time is the delay time for pedestrians plus crossing time



LinSig Results – Animation Mode







LinSig Overview

Other Features



LinSig Model Auditing – Model Audit View

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5	Frederi	Frederick Street / North Queen Stree		yes 1, 2, 3, 4, 5,		4, 5, 6, 7							
Lane	Arm Name	Lane Length (m)	Short/Long	Multi- lane?	Saturation Flow (PCU/Hr)	RR67?	Occupancy (PCU)	Associated Lane	Controlling Phase(s)	Start Displacement (s)	End Displacement (s)	sliver Threshold (PCU)	Ignore Random Delay
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LinSig Model Auditing Checksheets

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MODEL NAME MODEL STAGE		Fine Consider, not essential Needs addressing Note to auditor Requires checking at a later date Not checked, check not required			no action / response required action taken no action taken Still needs addressing Note to auditor		
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Zone Structure							
Vehicle Flows							
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Route List							
Phases (Street/controller,							
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stage sequence, stage green							
times)							
Cycle Times							
Intergreen Timings							
Phase Delays							
Bonus Greens							
Saturation Flows							
Optimisation							
Results (PRC, Delay, MMQ)							
Looking at model run							
Error File							
Calibration/Validation							
Comparison with PM model							





LinSig Overview

The future of LinSig



The future of LinSig

LinSig has developed into the industry leading package for modelling small and medium sized signalised networks.

The current version of LinSig (version 3) was released back in 2009, but it has been updated over the years.

JCT Consultancy are looking to release version 4 in 2022, but the release has been delayed.

Version 4 is supposed to have some microscopic simulation function to model complex blocking back issues at standalone junctions, so Version 3 will still be used in the short term for simple LinSig modelling.





LinSig Overview

AECOM's LinSig capability

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AECOM's LinSig Modelling Capability

AECOM has approximately 150 users of the software in 26 offices around the UK and Ireland.

Training has also been undertaken with AECOM staff from the GDC in Bangalore, India





AECOM's LinSig Training Capability

- "Introduction to LinSig" one-day training course has been run 32 times since 2012, training about 260 people, including people from outside AECOM
- "Advanced LinSig Features" one-day training course has been recently been added to training offering
- A two-part "Introduction to LinSig" bitesize course was run on Teams during the Covid Pandemic







Thank you.

Please feel to get in touch to discuss any modelling issues

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